



Head Office : Sree Sindhi Guru Sangat Sabha Association, # 4-1-1236/1/A, King Koti, Abids, Hyderabad - 500001.

Ph: 040-23234418, 040-2324419, 040-2324420, 040-24750437

Hyderabad | Kukatpally | Kothapet | Delhi | Bhopal | Patna | Pune | Bhubaneswar | Lucknow | Bengaluru | Chennai | Vijayawada | Vizag | Tirupati | Kolkata | Ahmedabad

Branch: Electrical Engineering

Time: 3 Hours

PRE- GATE-2020

Marks: 100

GATE-2020 Gene	ral Aptitude (GA)
INEER	ING
Q. 1 – Q. 5 carry ONE mark each.	Ans: (C)
	Sol: Troop consists of monkeys just as a colony
01. Fill in the blank with an appropriate	consists of bacteria.
phrase	
Jobs are hard to these days	03. Choose the most appropriate word from
(A) Come by (B) Come down	the options given below to complete the
(C) Come of (D) Come from	following sentence:
Ans: (A)	If you had gone to see him, he
Sol: 'Come by' means to manage to get	delighted.
something.	(A) Would have been
	(B) Will have been
02. The question below consists of a pair of	(C) Had been
related words followed by four pairs of	(D) Would be
words. Select the pair that best expresses	Ans: (A)
the relation in the original pair.	Ans: 'A" conditional tense type 3 grammatical
MONKEY : TROOP:	code is
(A) sheep : hard	If +had+V3, would +have+V3
(B) elephant : Parliament	
(C) bacteria : Colony	
(D) wolves : School	

04. Which of the following options is closest in meaning to the underlined word? European intellectuals have long debated

the consequences of the <u>hegemony</u> of American popular culture around the world.

- (A) regimen (B) vastness
- (C) dominance (D) popularity

Ans: (C)

- **Sol:** Dominance means influence or control over another country, a group of people etc.
- 05. How many one-rupee coins, 50 paise coins25 paise coins in total of which the numbers are proportional to 5, 7 and 12 are together work ₹115?
 - (A) 50, 70, 120
 (B) 60, 70, 110
 (C) 70, 80, 90
 (D) None of these

Ans: (A)

Sol:
$$(5 \times 1 + 7 \times 0.5 + 12 \times 0.25) = 115$$

- (5+3.5+3)x = 115
- 11.5x = 115
 - x = 10
- $\therefore \text{ Number of one rupee coin} = 5x = 5 \times 10$ = 50

Number of 5-paise coin = $7x = 7 \times 10 = 70$ Number of 25-paise coin = $12x = 12 \times 10$

= 120

Since

Q. 6 – Q. 10 carry TWO marks each.

06. Critical reading is a demanding process. To read critically, you must slow down your reading and, with pencil in hand, perform specific operations on the text mark up the text with your reactions, conclusions, and questions, then you read, become an active participant.

This passage best supports the statement that (A)Critical reading is a slow, dull but essential process.

- (B) The best critical reading happens at critical times in a person's life.
- (C) Readers should get in the habit of questioning the truth of what they read.
- (D)Critical reading requires thoughtful and careful attention.

Ans: (D)

Sol: Choice (A) is incorrect because the author never says that reading is dull.

Choice (B) and (C) are not support by the paragraph.

Choice (D) is correct as it is implied in the entire passage.

07. Anil's house faces east. From the back-side of the house, he walks straight 50 metres, then turns to the right and walks 50m again finally, he turns towards left and stops after walking 25 m Now Anil is in which direction from the starting point?



ESE – MAINS Classes Start from: 13th FEB 2020

Students who Qualify in Prelims can avail 100 % Fee Waiver



ESE-2018, 2019 Prelims Qualified Students are also eligible for Fee Discounts



@ DELHI







/aceenggacademy

- H.O. # 4-1-1236/1/A, Sindhu Sadan, King Koti Road, Abids, Hyderabad 500001, Telangana, India.
- Ph: 040-23234418/19/20 , 040-24750437.
- Email: hyderabad@aceenggacademy.com
- www.aceenggacademy.com



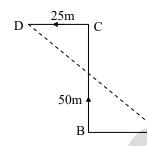
GATE-2020 Electrical Engineering (EE)

(C) North-east (D) North- west

Ans: (D)

(

Sol: The movement of Anil are shown in the adjoining figure



He starts walking from back of his house (i.e) towards west now, the final position is D, which is to the north west of his starting point A.

08. A and B enter into a partnership, A puts in ₹
50 and B puts in ₹ 45. At the end of 4 months, A withdraws half his capital and at the end of 5 months B withdraws 1/2 of his, C then enters with a capital of ₹ 70. At the end of 12 months, the profit of concern is ₹
254, how can the profit be divided among A, B and C?
(A) ₹ 76, ₹ 80 and ₹ 98
(B) ₹ 80, ₹ 76 and ₹ 98
(C) ₹ 76, ₹ 98 and ₹ 80

(D) None of these

Ans: (B)

Sol:	A's share	:	B's share	:	C's share
	(50×4+25×8)	:	(45×5+22.5×7) :	: (70×7)
	400	:	382.5	:	490
	800	:	765	:	980
	160	:	153	:	196

Total profit = ₹ 254

Profit of A =
$$\frac{160}{160 + 153 + 196} \times 254$$

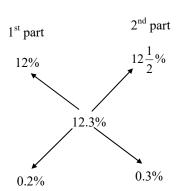
$$=\frac{160}{509}$$
 × 254 = ₹80

Profit of B = $\frac{153}{509} \times 254 = ₹76$

Profit of C =
$$\frac{196}{509}$$
 × 254 = ₹98

·· Hence option 'B' is correct.

09. A sum of ₹25400 was lent out in two parts, one of 12% and the other at $12\frac{1}{2}$ % of the total annual income is ₹3124.2, the money lent at 12% is _____. (A) ₹15240 (B) ₹25400 (C) ₹10160 (D) ₹31242 Ans: (C) Sol: Overall rate of interest $\frac{3124.2}{25400} \times 100 = 12.3\%$



- \therefore The sum will be divided in the ratio 0.2:0.3 (or) 2:3
- \therefore The sum lent at 12% = 25400 $\times \frac{2}{5}$

=₹10160.

10. The following question is to be answered on the basis of the table given below.

Number of	Number of
staff in the	staff in the
year-1990	year-1995
18	²⁵ since
5	8
18	32
21	26
15	31
3	3
80	135
	staff in the year-1990 18 18 5 18 21 15 3

What is the increase in the sector angle for operators in the year 1995 over the sector angle for operators in the year 1990?

Ans: (A)

Sol: Sector angle for operators in the year 1990

$$=\frac{18}{80}\times 360^\circ = 81^\circ$$

Sector angle for operator in the year 1995

$$=\frac{32}{135}\times 360^\circ = 85.33 \simeq 85\%$$

(B) 3°

 \therefore Required difference = $85^{\circ} - 81^{\circ} = 4^{\circ}$

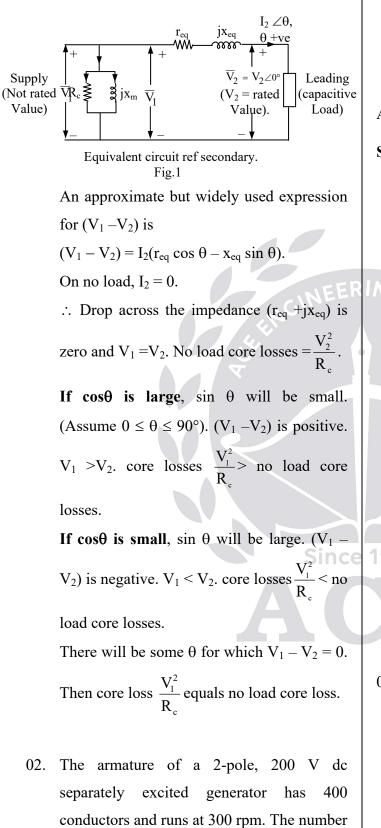
Q. 1 – Q. 25 carry ONE mark each.

- 01. A 2 winding transformer supplies a leading power factor load at rated secondary voltage. For a given load current, if magnitude of the load power factor varies, the core losses, as compared with the no load core losses, will
 - (A) remain unchanged.
 - (B) increase.
 - (C) decrease.
 - (D) either increase, remain constant, or decrease.

Ans: (D)

Sol: Assume (for simplicity) that the approximate equivalent circuit shown in fig.1 correctly represents the transformer.





is opened. If the field flux dies away completely in 0.075 sec, average field induced emf during the 0.075 sec period is V. Ans: (1600) **Sol:** 1. $K = \frac{PZ}{2\pi A} = \frac{400}{2\pi} = \frac{200}{\pi}$. 2. Initial operation: $2.1. \omega = 300 \times \frac{2\pi}{60} = 10\pi \text{ r/sec(mech)}$ 2.2.Flux/pole = ϕ (unknown). 2.3. E = $\frac{200}{\pi} \phi (10\pi) = 200$ (from given data). $\therefore \phi = 0.1$ Wb. The field flux decreases from $\phi = 0.1$ 3. Wb zero to in 0.075 sec. $\frac{\mathrm{d}\phi}{\mathrm{d}t}\bigg|_{\mathrm{ave}} = \frac{0.1}{0.075} = \frac{4}{3} \,\mathrm{Wb/sec.}$ (Ignore the negative sign). With 1200 field turns, average field 4. induced emf during the period $= 1200 \times \frac{4}{3} = 1600$ V.

03. A 3- ϕ star connected 400 V (line to line), 8 kW (output) synchronous motor with full load efficiency of 88% operating with minimum possible current. The synchronous impedance per phase is 8 Ω with negligible resistance. The induced

of field turns are 1200. Now the field circuit



Upcoming Batches @ H YDERABAD

GATE+PSUs-2021

- : 10th May, 8th & 23rd June 2020. Spark Batches
- : 26th April, 10th, 24th May, 8th, 23rd June, 7th, 22nd July, **Regular Batches** 5th & 20th August 2020.

ESE+GATE+PSUs-2021

Spark Batches : 10th May, 8th & 23rd June 2020. Regular Batches : 29th March, 26th April, 10th, 24th May, 8th, 23rd June & 7th July 2020.

SSC-JE Batches @ Hyderabad

New Batch Starts from: 10th May 2020

for Civil, Mechanical & Electrical

GATE+PSUs-2022 Weekend Batches ESE+GATE+PSUs-2022 Weekend Batches



Scan QR Code for **Upcoming Batches Details**

www.aceenggacademy.com

GATE+PSUs-2021

: 28th Dec, 11th Jan & 8th Feb 2020. Weekend Batches : 17th Feb, 7th March, 10th & 20th May 2020. **Regular Batches**

ESE+GATE+PSUs-2021

Weekend Batches : 28th Dec, 11th Jan & 8th Feb 2020. **Regular Batches**

: 17th Feb, 7th March, 10th & 20th May 2020.

: 28th Dec. 11th Jan & 8th Feb 2020.

: 28th Dec, 11th Jan & 8th Feb 2020.





emf/ph is	
(A) 233.7 V	(B) 238.7 V
(C) 248.7 V	(D) 253.7 V

Ans: (D)

Sol:
$$V_L = 400 \text{ V} \implies V_{ph} = \frac{400}{\sqrt{3}} = 231 \text{ V}$$

Motor output = 8 kW

$$P_{in} = \frac{P_{out}}{\eta} = \frac{8 \text{ kW}}{0.88} = 9091 \text{ W}$$

$$P_{in} = \sqrt{3} \text{ V}_{L} I_{L} \cos \phi \text{ ; current will be}$$
minimum at upf
$$\therefore I_{L} = \frac{P_{in}}{\sqrt{3} \text{ V}_{L}} = \frac{9091}{\sqrt{3} \times 400} = 13.12 \text{ A}$$

$$E = \sqrt{(\text{V} \cos \phi - I_{a} \text{ R}_{a})^{2} + (\text{V} \sin \phi \mp I_{a} \text{ X}_{s})^{2}}$$

$$= \sqrt{(231 \times 1 - 0)^{2} + (231 \times 0 + 13.12 \times 8)^{2}}$$

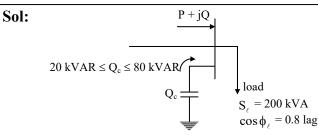
$$= 253.7 \text{ V}$$

04. A variable shunt capacitor bank of reactive power rating 'Q_c' connected in parallel with a load.

The load consumes an apparent power of 200 kVA at 0.8 power factor lagging. The reactive power ' Q_c ' varies as 20 kVAR $\leq Q_c \leq$ 80 kVAR. The combination of capacitor bank and load will draw the lowest apparent power from connected bus bar for any value of ' Q_c ' is

(A) 165 kVA	(B) 188 kVA
(C) 200 kVA	(D) 212 kVA

Ans: (A)



Load real and reactive power consumptions, $P_{\ell} = S_{\ell} . \cos \phi_{\ell} = 200 \times 0.8 = 160 \text{ kW}$ $Q_{\ell} = S_{\ell} . \sin \phi_{\ell} = 200 \times 0.6 = 120 \text{ kVAR}$ Net real power drawn, $P = P_{\ell} = 160 \text{ kW}$ Net reactive power drawn, $Q = Q_{\ell} - Q_{C}$ $= 120 - Q_{C}$ Net apparent power, $S = \sqrt{P^{2} + Q^{2}}$

 $= \sqrt{160^2 + (120 - Q_{\rm C})^2}$

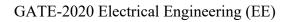
Minimum net apparent power (S_{min}) occurs for lowest value of 'Q' or highest value of 'Qc'

$$S_{min} = \sqrt{(160)^2 + (120 - 80)^2}$$

= 165 kVA

1995

05. A 150 bus power system network consists 25 generator buses, 5 buses having fixed shunt capacitor banks, 3 buses having SVC's, 2 buses having STATCOM's and remaining buses are treated as load buses. How many number of equations to be solved in load flow analysis of this system by Gauss Seidel method and Newton Raphson method (rectangular form) respectively



(B) 150, 298

(A) 150, 264



ACE Engineering Academy



The switching energy loss (in mJ) during turn on is ______. (Give upto one decimal place)

Ans: 1.985 (Range: 1.9 to 2.1)

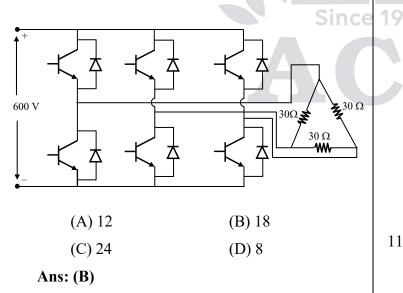
Sol:
$$I_c = \frac{V_{cc} - V_{CE(sat)}}{R_c}$$

= $\frac{200 - 1.5}{10} = 19.85 \text{ A}$

Turn ON energy loss = $\frac{V_{cc}I_c}{6} \times T_{on}$ = $\frac{200 \times 19.85}{3} \times 3 \times 10^{-6}$

$$= 1.985 \text{ mJ}$$

09. A three-phase voltage source inverter (VSI) as shown in the figure is feeding a delta connected resistive load of 30Ω /phase. If it is fed from a 600 V battery, with 120° conduction of solid-state device, the power consumed by the load, in kW, is



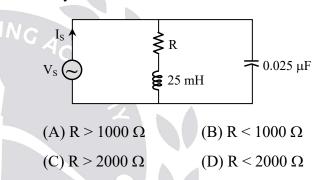
Sol: RMS value of phase voltage for 120° conduction mode is

$$V_{L} = V_{Ph} = \frac{V_{dc}}{\sqrt{2}} = \frac{600}{\sqrt{2}}$$
 V

Power delivered to load

$$P_o = 3 \times \frac{V_{ph}^2}{R} = 3 \times \frac{(600/\sqrt{2})^2}{30} = 18 \text{ kW}$$

10. Resonance will occur in the circuit shown only when



Ans: (B)

Sol: As resonance frequency

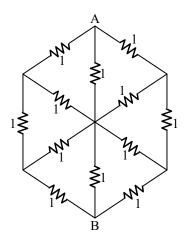
$$f_r = \frac{1}{2\pi\sqrt{LC}}\sqrt{1 - \frac{R^2C}{L}}$$

Resonance will occur in circuit only when

$$1 - \frac{R^{2}C}{L} > 0, 1 > \frac{R^{2}C}{L}, R^{2} < \frac{L}{C}$$
$$R < \sqrt{\frac{L}{C}}$$
$$R < \sqrt{\frac{25 \times 10^{-3}}{0.025 \times 10^{-6}}} = 1000 \Omega$$

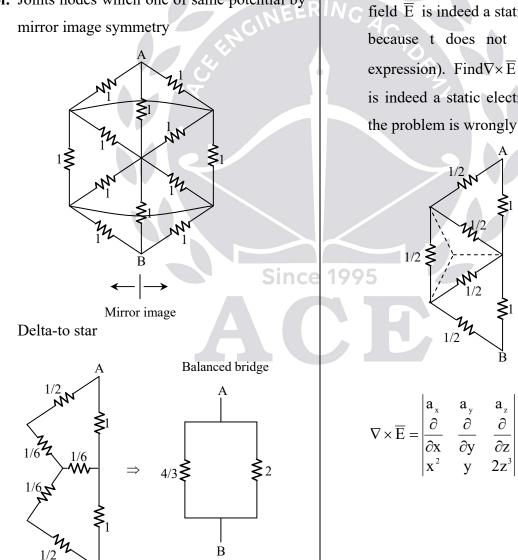
11. The resistance between terminals A, B is $_$ _____Ω.

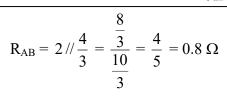




Ans: 0.8 (Range: 0.75 to 0.85)

Sol: Joints nodes which one of same potential by





12. An electric field $(x^2a_x + ya_y + 2z^3a_z)$ N/C exists in free space. Corresponding charge density at the origin is _____ $p C/m^3$. (rounded off to two decimal places).

Ans: 8.85 (Range: 8.84 to 8.86)

- Sol: It is useful to check that the given vector
 - field \overline{E} is indeed a static electric field (static because t does not appear in the field expression). Find $\nabla \times \overline{E}$. Is it zero? Then \overline{E} is indeed a static electric field. (Otherwise the problem is wrongly framed).

ACE Engineering Academy

GATE-2020 Electrical Engineering (EE)



$$= a_{x} \left\{ \frac{\partial}{\partial y} (2z^{3}) - \frac{\partial}{\partial z} (y) \right\} + a_{y} \left\{ \frac{\partial}{\partial z} (x^{2}) - \frac{\partial}{\partial x} (2z^{3}) \right\}$$
$$+ a_{z} \left\{ \frac{\partial}{\partial x} (y) - \frac{\partial}{\partial y} (x^{2}) \right\}$$
$$= 0$$

 \overline{E} is a static electric field.

Then,
$$\nabla . \overline{E} = \frac{\rho}{\varepsilon_0}$$
 (Gauss;s law)

But,

$$\Delta \overline{E} = \left(\frac{\partial}{\partial x}a_x + \frac{\partial}{\partial y}a_y + \frac{\partial}{\partial z}a_z\right) (x^2a_x + ya_y + 2z^3a_z)$$

$$= 2x + 1 + 6z^2$$
At origin (0, 0, 0), $\nabla \overline{E} = 1$.

$$\therefore \qquad \frac{\rho_{(0,0,0)}}{\epsilon_0} = 1$$

:.
$$\rho_{(0, 0, 0)} = \epsilon_0 = 8.854 \times 10^{-12} \text{ C/m}^3$$

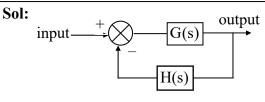
- Negative feedback is employed in a control system then which one of the following statement (s) is/are true.
 - 1. Gain increases
 - 2. Bandwidth increases

3. Sensitivity of the output with respect to parameter changes in the forward path decreases.

4. Time constant of the system decreases

(A) 1, 2, 3, 4	(B) Only 2, 3, 4
(C) Only 3, 4	(D) Only 2,4

Ans: (B)



$$CLTF = \frac{G(s)}{1 + G(s)H(s)}$$

Negative feedback reduces gain of system

$$S_G^M = \frac{1}{1 + G(s)H(s)}$$
 is less than unity

i.e., less sensitive to the forward path parameter variations.

Bandwidth increases hence rise time decreases, speed increases, time constant decreases.

14. State space representation of a system is given as

$$\dot{\mathbf{x}}(t) = \begin{bmatrix} -2 & 0 \\ 0 & -4 \end{bmatrix} \mathbf{x}(t) + \begin{bmatrix} 1 \\ -1 \end{bmatrix} \mathbf{u}(t), \mathbf{y}(t) = \begin{bmatrix} 1 & 1 \end{bmatrix} \mathbf{x}(t)$$

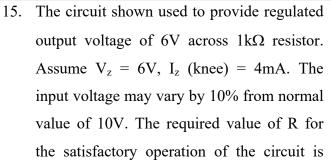
• Where y(t) is the output and u(t) is the input. Then the undamped natural frequency of the system is _____ rad/sec. (round up to two decimal places).

Ans: 2.83 (Range 2.8 to 2.9)

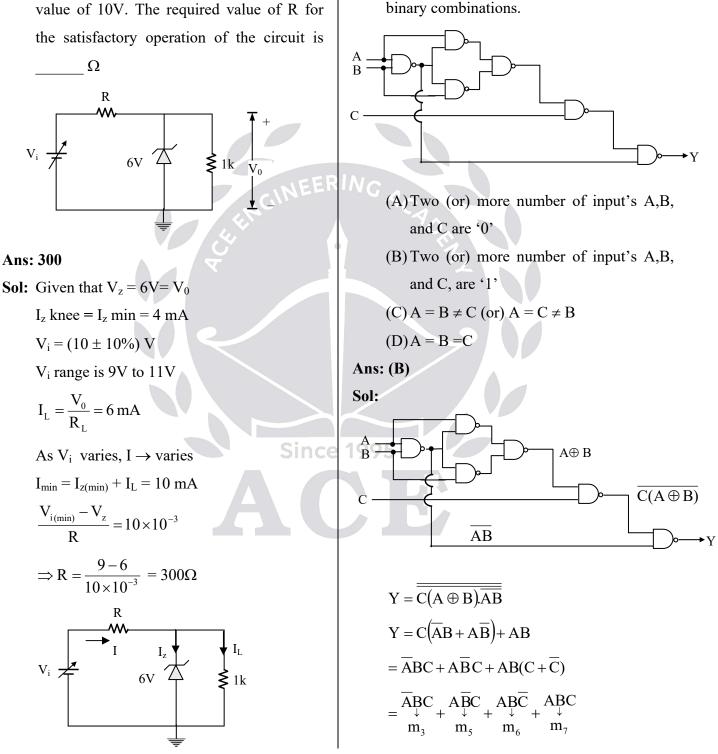
Sol: Characteristic equation (s+2)(s+4) = 0 $s^2 + 6s + 8 = 0$

$$\omega_n^2 = 8$$

 $\omega_n = 2\sqrt{2} \text{ rad/sec} = 2.83 \text{ rad/sec}$



16. A, B, and C are Input bits and 'Y' is the output bit in the circuit shown below. If the output 'Y' is set to logic '1', which of the following option can satisfies the input



ACE Engineering Academy



Hyderabad | Ahmedabad | Kothapet | Kukatpally | Delhi | Pune | Bhubaneswar | Lucknow | Bengaluru | Chennai | Vijayawada | Vizag | Tirupathi | Kolkata

ESE/GATE/PSUs LONG TERM PROGRAM **@ HYDERABAD Batches Start From** 9th JAN 2020 25th FEB 2020 Streams Offered : EC | EE | ME | CE | CSIT | IN & PI **MORNING BATCHES EVENING BATCHES WEEKEND BATCHES** a a a ABIDS KUKATPALLY, KUKATPALLY, **ABIDS** DILSUKHNAGAR DILSUKHNAGAR (HERITAGE BLOCK) (HERITAGE BLOCK) New Batches for New Batches for **COURSES OFFERED:** ESE + GATE + PSUs - 2021 ESE + GATE + PSUs - 2022 Morning Batches @ Abids Classroom Coaching **GATE + PSUs - 2022** 28th DEC & 19th JAN 2020 Postal Coaching Starts from: 1 Online Test Series 19th JAN 2020 25th FEB 2020 Interview Guidance Scan **QR CODE** for New Batch Details Digital Classes Hearty Congratulations to our ESE 2019 Top Rankers our GATE-2019 Rankers HARSHAL BHOSALE ABUZAR GAFFARI ABIDS **KUKATPALLY** DILSUKHNAGAR ഭ 040-23234418,19,20, 040-24750437 <u>ଳ</u> 040-40199966, 93476 99966 ₷ 040-40209345, 040-40044451

www.aceenggacademy.com | follow us on: **D** (f) (0) (2)



 18. The below program is stored from Address 0101H LXI H, 7788 H MOV A, L ANA H JPO SKIP ADD L SKIP: MOV H,A DAD H SHLD 1234H PCHL
LXI H, 7788 H MOV A, L ANA H JPO SKIP ADD L SKIP: MOV H,A DAD H SHLD 1234H
MOV A, L ANA H JPO SKIP ADD L SKIP: MOV H,A DAD H SHLD 1234H
ANA H JPO SKIP ADD L SKIP: MOV H,A DAD H SHLD 1234H
JPO SKIP ADD L SKIP: MOV H,A DAD H SHLD 1234H
ADD L SKIP: MOV H,A DAD H SHLD 1234H
SKIP: MOV H,A DAD H SHLD 1234H
DAD H SHLD 1234H
SHLD 1234H
PCHL
From which address next instruction will be
fetched?
(A) 0110H (B) 1111H
(C) 1110H (D) 1234H
Ans: (C)
Sol: * (HL) = 7788H
* (A) \leftarrow (L) = 88H
\Rightarrow (A) = 88H
$*(A) = 88H = 1000\ 1000$
1995 (H) = 77H = 0111 0111
(A) = 00H = 0000 0000
CY = O, P = 1, AC = 1, Z = 1, S = 0
* JPO means Jump if parity odd
i.e., test for $P = 0$
This test fails as $P = 1$ because of ANA H
Therefore, µp does not jump but continues
with next instruction.

Т

GATE-2020 Electrical Engineering (EE)



*(A) = 00H = 0000 0000
$+(L) = +88H = 1000 \ 1000$
$\underline{(A)} = \underline{88H} = \underline{1000 1000}$
$*$ (H) \leftarrow (A) = 88H
\Rightarrow (H) = 88H
(HL) = 8888H = 1000 1000 1000 1000
$+(HL) = 8888H = 1000 \ 1000 \ 1000 \ 1000$
$\underline{(HL)} = \underline{1110H} = \underline{0001 \ 0001 \ 0001 \ 0000}$
* (HL) = 1110 H stored into 2 locations
1234Н
And E
1235Н

$$*$$
 (HL) = 1110 H copied into P.C

 \Rightarrow (P.C) = 1110H

 \therefore 8085 µP fetches next instruction from

Address 1110H

19. An LTT system with impulse response

$$h(t) = \frac{1}{\sqrt{t+2}}u(t+1) i$$

- (A) Causal & Stable
- (B) Causal & Unstable
- (C) Unstable & Non causal
- (D) Non causal & Stable

Ans: (D)

Sol:
$$h(t) = \frac{1}{\sqrt{t+2}}u(t+1)$$

Because the signal (IR) starts at $t = -1 \Rightarrow$ Non causal.

For the stability
$$\int_{-\infty}^{\infty} |h(t)| dt < \infty$$

 $\int_{-1}^{\infty} \frac{1}{\sqrt{t+2}} dt < \infty$ \therefore Stability
 \therefore The system is stable & NC
20. An FIR system with input x(n) and output
y(n) related as y(n) = 0.2x(n) -0.5x(n - 2) +
0.4x(n-3). If the input x(n) = {-1, 1, 0, 1}
is applied then the output at n = 2 is
Ans: 0.5
Sol: y(n) = 0.2x(n) - 0.5 x(n-2) + 0.4 x(n-3)
y(2) = 0.2x(2) - 0.5 x(0) + 0.4 x(-1)(1)
x(n) = {-1,1,0,1}
x(0) = -1, x(1) = 1; x(2) = 0
x(3) = 1
Substituting in equation (1)
y(2) = 0.2(0) - 0.5 (-1) + 0.4 (0)=0.5
 \therefore y(2) = 0.5
21. Two LTI systems with impulse response
h_1(n) = δ (n) and h_2(n) = δ (n) - δ (n-2) are
connected in cascade. If the input x(n) =
u(n) is applied then the output is
(A) δ (n) (B) δ (n-1)
(C) δ (n) + δ (n-1) (D) δ (n-1) + δ
(n-2)

Ans: (C)

Since

21.

20.

Sol: Two systems are connected in cascade the



GATE-2020 Electrical Elignicering (EE)	Comparing Publications
overall IR is	23. If directional derivative of $\phi = 2xz - y^2$, at
$h(n) = h_1(n) * h_2(n)$	the point (1, 3, 2) becomes maximum in the
$h(n) = \delta(n) * [\delta(n) - \delta(n-2)]$	direction of \overline{a} , then magnitude of \overline{a} is
$h(n) = \delta(n) - \delta(n-2)$	(Give upto two decimal place)
$\mathbf{y}(\mathbf{n}) = \mathbf{x}(\mathbf{n}) * \mathbf{h}(\mathbf{n})$	Ans: 7.48 (Range 7.45 to 7.50)
$y(n) = u(n) * [\delta(n) - \delta(n-2)]$	Sol: Given $\phi = 2xz - y^2$
y(n) = u(n) - u(n-2)	$\nabla \phi = \frac{\partial \phi}{\partial x} \overline{i} + \frac{\partial \phi}{\partial y} \overline{j} + \frac{\partial \phi}{\partial z} \overline{k}$
$=\{1, 1\}$	$\partial x \partial y \partial z$
	$= 2z\overline{i} - 2y\overline{j} + 2x\overline{k}$
$y(n) = \delta(n) + \delta(n-1)$	\therefore Required direction vector = $\overline{a} = (\nabla \phi)$ at
IN EE	R ING (1, 3, 2) = $(4\overline{i} - 6\overline{j} + 2\overline{k})$
22. For the function $f(x, y) = x^2 - y^2$, the point	Magnitude of $\overline{a} = \sqrt{16 + 36 + 4} = \sqrt{56}$
(0, 0) is	= 7.48
(A) a local minimum	- 7.40
(B) a saddle point	24. A continuous random variable X has a
(C) a local maximum	
(D) not a stationary point	probability density function $f(x) = e^{-X} + 0 (and for a probability of the probab$
Ans: (B)	$f(x) = e^{-x}, 0 < x < \infty$. Then $P(X > 2)$ is
Sol: Given $f(x, y) = x^2 - y^2$	(A) 0.1353 (B) 0.2354 (D) 1.1252
\Rightarrow f _x = 2x, f _y = -2y and	(C) 0.2343 (D) 1.1353
$f_{xx} = 2, f_{xy} = 0, f_{yy} = -2$ Sinc	Ans: (A)
	Sol: $P(X > 2) = \int_{-\infty}^{\infty} f(x) \cdot dx$
Consider $f_x = 0$ and $f_y = 0$	
$\Rightarrow 2x = 0 \text{ and } -2y = 0$	$=\int_{0}^{\infty}e^{-x}dx$
\Rightarrow (0,0) is a stationary point	2
At (0, 0), $f_{xx} f_{yy} - (f_{xy})^2 = -4 < 0$	$=\frac{e^{-x}}{ x }^{\infty}$
\therefore f(x, y) has neither a maximum nor	$\left -1 \right _2$
minimum at $(0, 0)$.	$=e^{-2}=0.1353$





HYDERABAD | DELHI | VIJAYAWADA | TIRUPATI | PUNE | BHUBANESWAR | BENGALURU | LUCKNOW | CHENNAI | VIZAG | KOLKATA | AHMEDABAD

ADMISSIONS ARE OPEN FOR ESE | GATE | PSUs - 2021 & 2022 @ DELHI

Streams: CE | ME | EC | EE | CS | IT | IN | PI

WEEKEND BATCHES START FROM

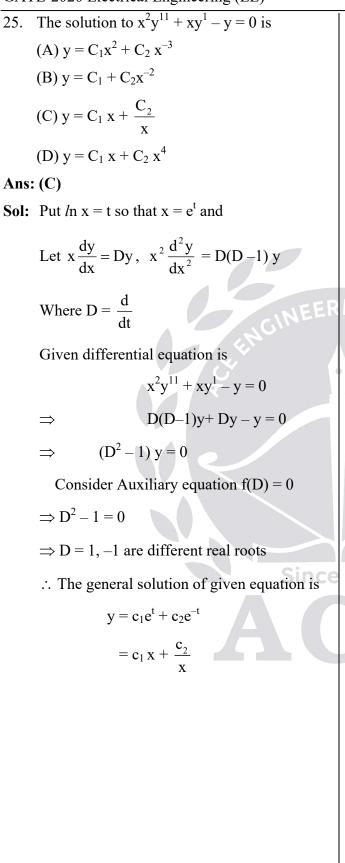
11th JAN 2020 8th FEB 2020

Special Discounts for Weekend Batches @ DELHI **Group Discounts** College/Branch Topper Individual Discounts Colleges Rank1&2 % 0/0 % IIT OFF **OFF OFF** on Tuition Fee on Tuition Fe on Tuition Fee % <mark>0/0</mark> % NIT/DTU/NSUT 5 OFF ARMED FORCES OFF OFF DIFFERENTLY ABLED **IIIT/IGDTUW** 25 % % ⁰/0 JMI/USICT YMCA/DCRUST OFF OFF UIET (MDU & KUK) on Tuition Fee on Tuition Fee n Tuition Fee 0/0 % 25 % % Also, Special Discounts Other Govt. IJ OFF OFF Engg. Colleges for Previously Qualified n Tuition Fee **Tuition** Fee ESE (Prelims/Mains) / GATE Students % 0/0 0/0 IPU/AKTU for more details visit our website: MDU/KUK OFF OFF **OFF Affiliated Colleges** on Tuition Fee on Tuition Fee www.aceenggacademy.com

Call Us Today for Career Counselling : 7838971777 | Email: delhi@aceenggacademy.com

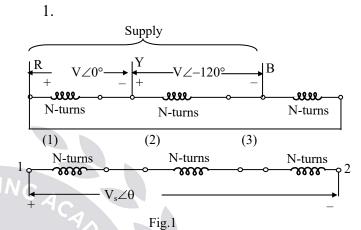
Terms & Conditions Apply





Q. 26 - Q. 55 carry TWO marks each.

26. Three identical 2-winding single-phase transformers are connected as shown in fig.

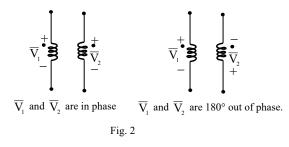


The two possible values for V_s are,

(A) 3V, V	(B) 0, 2 V
(C) 0, V	(D) 0, $2V \angle -60^{\circ}$.
26. Ans: (B)	

Sol: Fig. 1 of the question does not give any information about the relative polarities of the primary and secondary voltages. (This information is usually given by placing dots at the two windings of each of the transformers as per the dot convention. Such dots are not placed any where).

One meaning of dots (which is needed for this problem) is as follows:





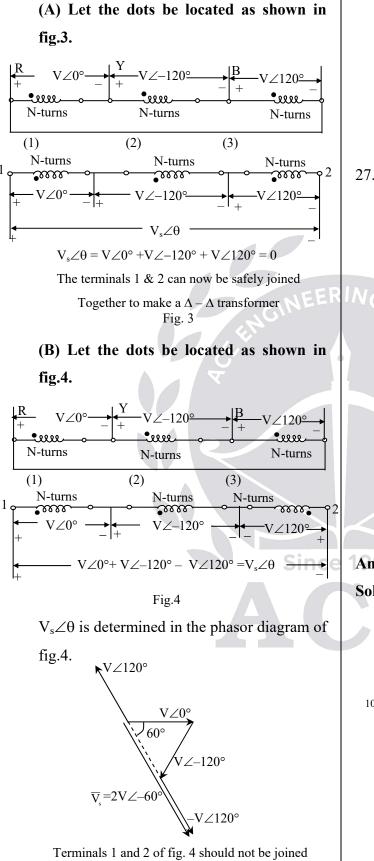


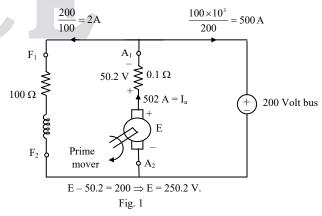
Fig. 5.

There are several other ways of connecting the three secondaries. Everyone of them leads to either $V_s = 0$ or $V_s = 2V$.

Thus there are only two possible values for V_s : Zero, and 2V.

- A 100 kW, belt-driven dc shunt generator is 27. running at 300 rpm in the clockwise direction, delivering power to a 200 V bus. Now the belt breaks, but the machine continues to run, drawing 4 kW from the supply. Neglect armature reaction. Armature and field resistances are 0.1 Ω and 100 Ω respectively. Its speed and direction of rotation after the belt breaks are, respectively.
 - (A) 238, clockwise
 - (B) 238, anti clockwise
 - (C) 242, clockwise
 - (D) 242, anti clockwise
- Ans: (A)







For a field current of 2A, let the flux/pole be φ Wb.

$$k\phi\left(300\times\frac{2\pi}{60}\right) = 250.2 \implies k\phi = \frac{25.02}{\pi}$$

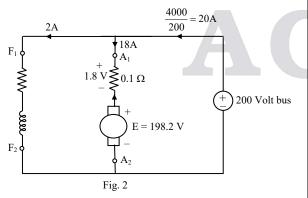
The armature is given to be rotating in the cw direction.

2. Direction of developed torque during the initial operation:

With the armature and field currents directed as shown in fig.1, **the developed torque in the machine must be in the anti clock wise direction.** This is because the prime mover, in driving the armature in the clock wise direction, has to do mechanical work against the developed torque, which work is converted into electrical energy and losses by the machine.

3. Operation after the belt breaks:

Steady state conditions after the belt breaks are specified the problem. Corresponding circuit is as shown in fig. 2.



With field current unchanged, $k\phi$ remains unchanged at $\frac{25.02}{\pi}$. (Since armature reaction is neglected, change in armature current from 502 A to 18 A does not affect the flux/pole in any way).

$$\left(\frac{25.02}{\pi}\right) N\left(\frac{2\pi}{60}\right) = 198.2$$

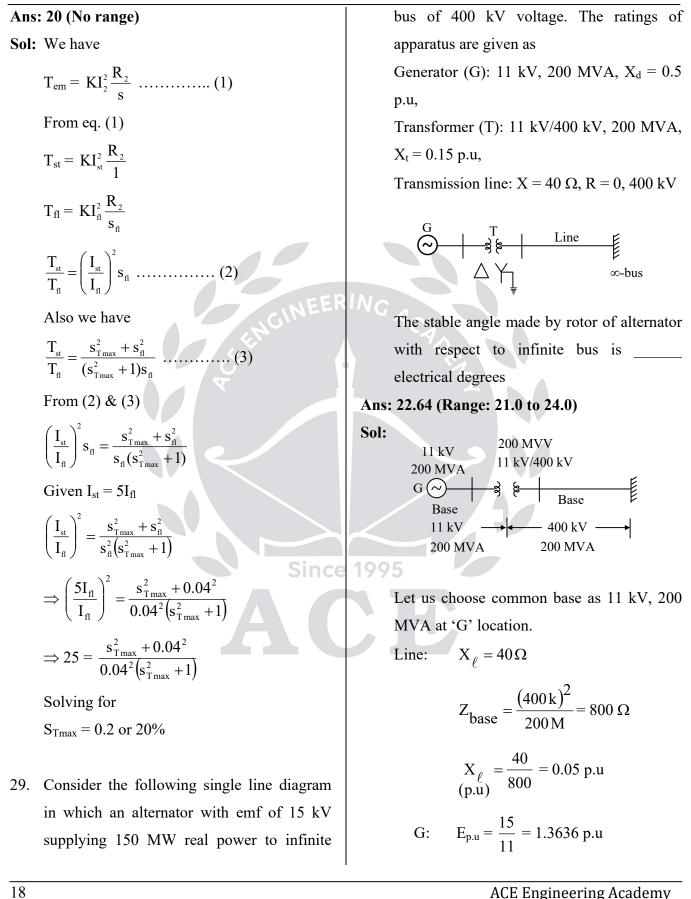
 \Rightarrow N = 237.65rpm \approx 238 rpm.

When belt breaks, there is no prime mover anymore. However, the stored kinetic energy in the rotor keeps the rotor running in the clock wise direction, but with decreasing speed. The machine is in regenerative braking mode, which continues as long as E in fig.1 is greater than 200V, and I_a of fig. 1 is positive (developed torque will be in acw direction, it opposes motion and causes speed to fall). When E becomes less than 200 V, as in fig. 2, I_a reverses. With I_f continuing to be in the original direction, T_d is now in the clock wise direction, and drives the machine in the clock wise 199 direction as a motor.

238 rpm, clock wise; is the correct answer.

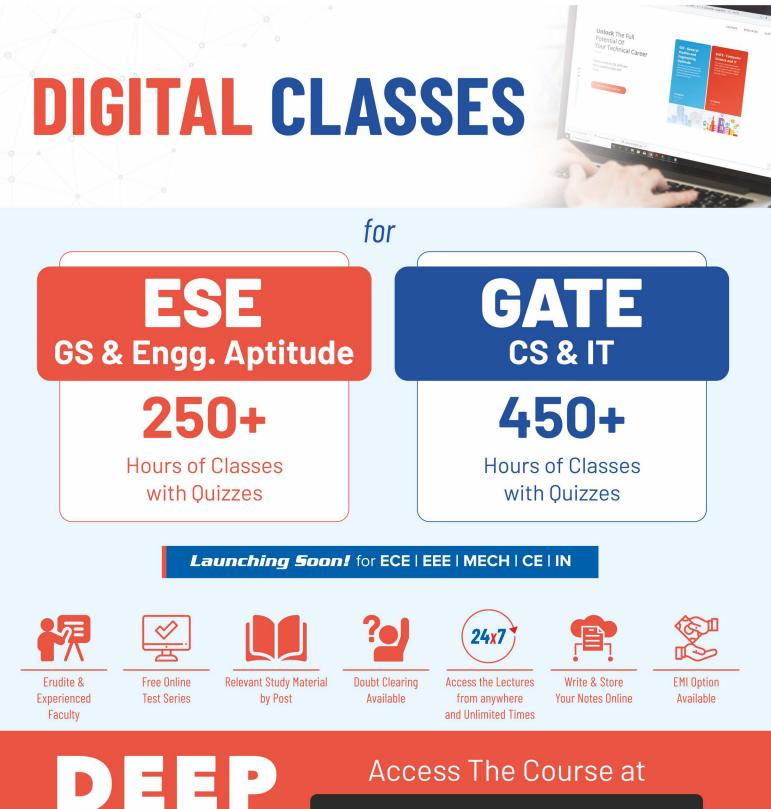
28. A squirrel cage induction motor has slip of 4% at full load. Its starting current is five times the full load current. The stator impedance and magnetizing current may be neglected, the rotor resistance is assumed constant. The percentage of slip at which maximum torque occurs is _____.











www.deep-learn.in

Call: 040-23234418/19/20 | web: www.aceenggacademy.com

LEARN



Infinite bus:
$$V_{p.u} = \frac{400}{400} = 1 \text{ p.u}$$

The per phase equivalent circuit is given as,

$$\overset{jX_{d}}{\longrightarrow} \overrightarrow{E} = |E| \angle \delta \qquad \qquad \overset{jX_{t}}{\longrightarrow} \overrightarrow{V} = |V| \angle 0^{\circ}$$

Real power flow, P = 150 MW

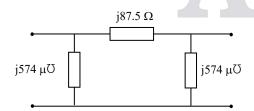
$$P_{(p.u)} = \frac{P}{S_{base}} = \frac{150}{200} = 0.75 \text{ p.u}$$

$$P = \frac{|E||V|}{X_{eq}} . \sin\delta$$

Where $X_{eq} = X_d + X_t + X_{\ell} = 0.7 \text{ p.u}$

$$0.75 = \frac{1.3636 \times 1}{0.7} \sin \delta \implies \delta = 22.64^{\circ}$$

30. A 3- ϕ loss less transmission line has the propagation constant $\gamma = 0 + j1.06 \times 10^{-3}$ radians per km. The transmission line is represented in its equivalent π model as shown in the figure.



The approximate length of transmission line is _____ km.

Ans: 300 (Range: 295 km to 305 km)

Sol: Equivalent- π model,

$$\frac{z'}{\frac{y'}{2}}$$

Parameter A =
$$1 + \frac{z'y'}{2}$$

For transmission line, $A = \cos\beta \ell$

$$\therefore \cos \beta \ell = 1 + \frac{z' y'}{2}$$

= 1+ (j87.5 × j574 × 10⁻⁶)
= 0.9498
 $\beta \ell = \cos^{-1} (0.9498)$
 $\beta \ell = 0.31828$ radians

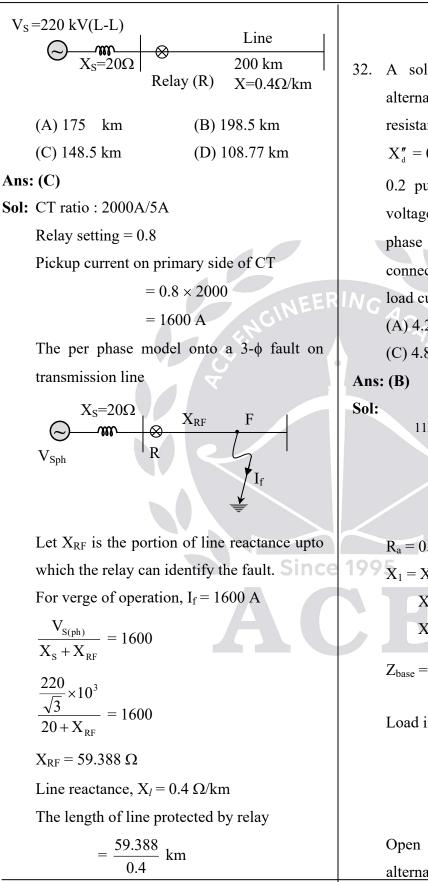
Where
$$\beta = 1.06 \times 10^{-3} \text{ rad/km}$$

 $\therefore \ \ell = \frac{0.31828}{1.06 \times 10^{-3}} \text{ km} = 300 \text{ km}$

31. A transmission line of length 200 km with series reactance per km as 0.4 Ω is supplied by a source of 220 kV (LL) with source reactance of 20 Ω . The line is protected by a over current relay (R) with relay setting 80% and associated with a CT of ratio 2000/5A.

The relay will provide protection for ______ length of transmission line for three phase fault on transmission line. GATE-2020 Electrical Engineering (EE)

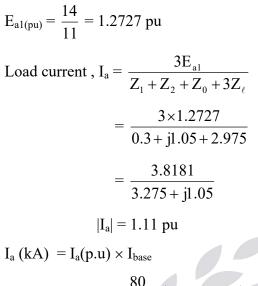




•	A solidly grounded neutral Y-connected
	alternator rated for 11 kV, 80 MVA has the
	resistance and reactances as $R_a = 0.1$ pu,
	$X''_{d} = 0.2 \text{ pu}, \ X'_{d} = 0.4 \text{ pu}, \ X_{d} = 0.8 \text{ pu}, \ X_{2} =$
	0.2 pu, $X_0 = 0.05$ pu. The open circuit
	voltage of alternator is 14 kV(LL). A single
	phase load of impedance $1.5 + j0 \Omega$ is
	connected at the terminals of alternator. The
	load current is
9	(A) 4.23 kA (B) 4.66 kA
	(C) 4.85 kA (D) 5.39 kA
ns	: (B) Z
l:	
	11kV, 80 MVA
	$\lambda_{1} \Theta \longrightarrow $
	$R_a = 0.1 \text{ pu}$; $Z_1 = 0.1 + j0.8$
9	$X_1 = X_d = 0.8 \text{ pu}$; $Z_2 = 0.1 + j0.2$
	$X_2 = 0.2 \text{ pu}$; $Z_0 = 0.1 + j0.05$
	$X_0 = 0.05 \text{ pu}$
	$Z_{\text{base}} = \frac{(11)^2}{80} = 1.5125 \ \Omega$
	Load impedance in per unit, $Z_{l pu} = \frac{Z_{\ell}(\Omega)}{Z_{base}}$
	$=\frac{1.5}{1.5125}=0.9917$ pu
	Open circuit voltage (or) internal unit of

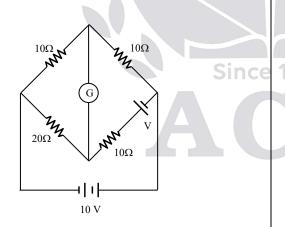
= 148.47 km

 $\frac{\text{alternator, } E_{a1} (LL) = 14 \text{ kV}}{\text{ACE Engineering Academy}}$

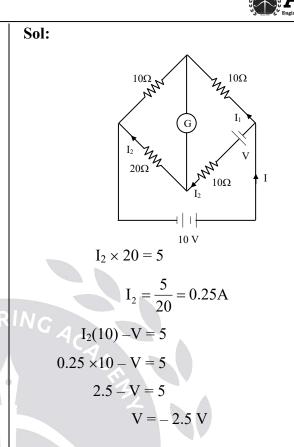


$$= 1.11 \times \frac{80}{\sqrt{3} \times 11} \text{kA} = 4.66 \text{ kA}$$

33. The resistance values of the bridge circuit shown in the figure are $R_1 = R_2 = R_3 = 10 \Omega$ and R_4 is 20 Ω . The bridge is balanced by introducing a voltage source of 'V' as shown in figure.



The value of voltage source is ______ volts.



34. A time varying voltage signal V(t) = X + Ysinot is measured by a single channel Analog CRO (operated with coupling mode set to DC) and also by Dual slope integrating DMM (operated with voltage Range set to AC). After measurement, DMM and CRO will display respectively are

(A)
$$\sqrt{\left(\frac{X}{\sqrt{2}}\right)^2 + \left(\frac{Y}{\sqrt{2}}\right)^2}$$
 & X+Y sinot

(C)
$$\sqrt{X^2 + \left(\frac{Y}{\sqrt{2}}\right)^2}$$
 & Ysinot

(D) X & Y sinwt

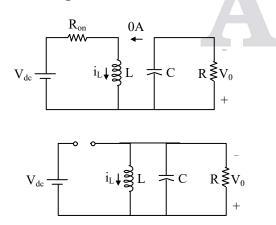
Sol: DMM measures average value. Therefore displays X
In DC coupling, the sensed signal as it is reaches to Y-input of CRO and hence displayed as X + Y sinωt.

35. A Buck-Boost converter is shown in figure. Assume that inductor and capacitor are large enough to treat i_L and V_0 are ripple free. MOSFET has ON resistance of 0.5Ω during its conduction. To maintain output voltage of 400V at 10A to the load, the duty cycle ratio of converter will be ______. (Give upto two decimal place)

$$V_{dc} = i_L \downarrow g L C = 400V +$$

Ans: 0.58 (Range: 0.56 to 0.60) Sol: During MOSFET ON:

During MOSFET OFF:



$$KVL: R_{on}i_{L} + L\frac{di_{L}}{dt} = V_{dc} \dots (1)$$

$$KVL: L\frac{di_{L}}{dt} = -V_{0} \dots (1)$$

$$KCL: C\frac{dv_{0}}{dt} + \frac{v_{0}}{R} = 0 \dots (2)$$

$$KCL: C\frac{dv_{0}}{dt} + \frac{v_{0}}{R} = i_{L} \dots (2)$$
Flux balance equation from KVL

$$\Rightarrow R_{on} I_{L} D + 0 = D.V_{dc} - V_{0}(1 - D) \dots (1)$$
Charge balance equation from KCL
$$\Rightarrow \frac{V_{0}}{R} = I_{L}(1 - D) \dots (2)$$
By substituting I_L value from equation (2) into equation (1), we will get
$$\Rightarrow R_{on} \cdot \frac{V_{0}}{R(1 - D)} D + V_{0}(1 - D) = D.V_{dc}$$

$$\Rightarrow V_{0} \left[\frac{R_{on}}{R} \times \frac{D}{1 - D} + (1 - D) \right] = DV_{dc}$$

$$\Rightarrow \frac{V_{0}}{V_{dc}} = \frac{D}{\frac{R_{on}}{R} \cdot \frac{D}{1 - D}} + (1 - D)$$
Now, substitute the given data
$$\frac{400}{300} = \frac{D}{\frac{0.5}{40} \times \frac{D}{1 - D}} + (1 - D)$$

$$\Rightarrow 560D^{2} - 876D + 320 = 0$$

ACE

 \Rightarrow D = 0.983 (or) 0.5813

Since 19

If D is near to unity, buck-boost converter will be unstable. Hence choose, 0.5813.

- 36. A single phase full wave half controlled rectifier is supplying an inductive load and assume current is ripple free at 10 A. It has been operated with firing angle delay of 45° then power factor on the AC supply lines is
 (A) 0.9238 (B) 0.8869
 - (C) 0.707 (D) 0.52

Ans: (B)

Sol: Single phase full wave half controlled rectifier is a semi converter.

Power factor = $C.D.F \times D.F$

$$C.D.F = \frac{I_{S1}}{I}$$

 $I_{S1} = \frac{2\sqrt{2}}{\pi} I_o \cos \frac{\alpha}{2}$ = 0.9 I_o cos $\frac{45^\circ}{2}$ = 8.315 A

$$I_{Sr} = I_o \sqrt{\frac{\pi - \alpha}{\pi}}$$

= 10 $\sqrt{\frac{180 - 45}{180}}$ = 8.66 A

$$C.D.F = \frac{8.315}{8.66} = 0.96$$

D.F =
$$\cos\frac{\alpha}{2} = \cos\frac{45^{\circ}}{2} = 0.9238$$

Power factor = $0.96 \times 0.9238 = 0.8869$

Since

37. A single phase 230V, 50Hz full wave rectifier consists of three diodes and one thyristor and supplying a resistive load of 10 Ω. The firing angle delay is so selected that



the average output current 20.7 A, then the peak value of fundamental supply current is ______ A (Give upto two decimal

places)

Ans: 32.52 (Range: 32 to 33)

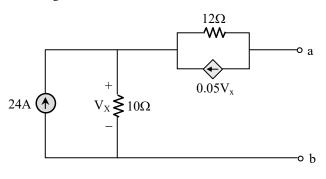
Sol: A single phase full wave rectifier consists of three diodes and one thyristor and supplying a resistive load, then

$$V_0 = \frac{V_m}{2\pi} [3 + \cos \alpha]$$
$$I_0 = \frac{V_o}{R} = \frac{V_m}{2\pi R} [3 + \cos \alpha]$$
$$\Rightarrow 20.7 = \frac{230 \times \sqrt{2}}{2\pi \times 10} [3 + \cos \alpha]$$
$$\Rightarrow \cos \alpha = 1$$
$$\Rightarrow \alpha = 0$$

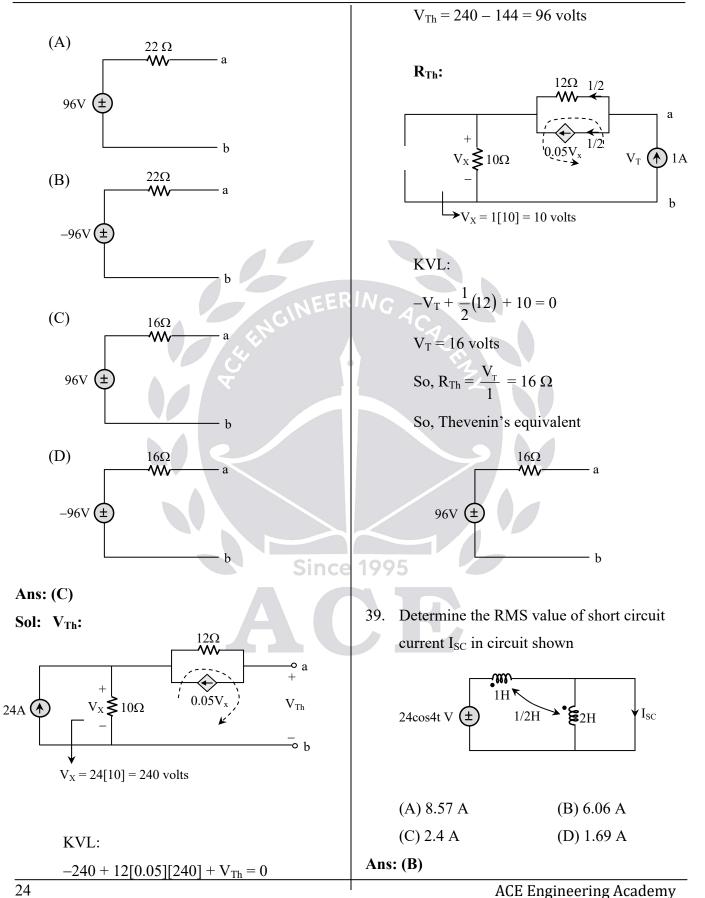
If $\alpha = 0$, then the shape of the supply current is pure sinusoidal.

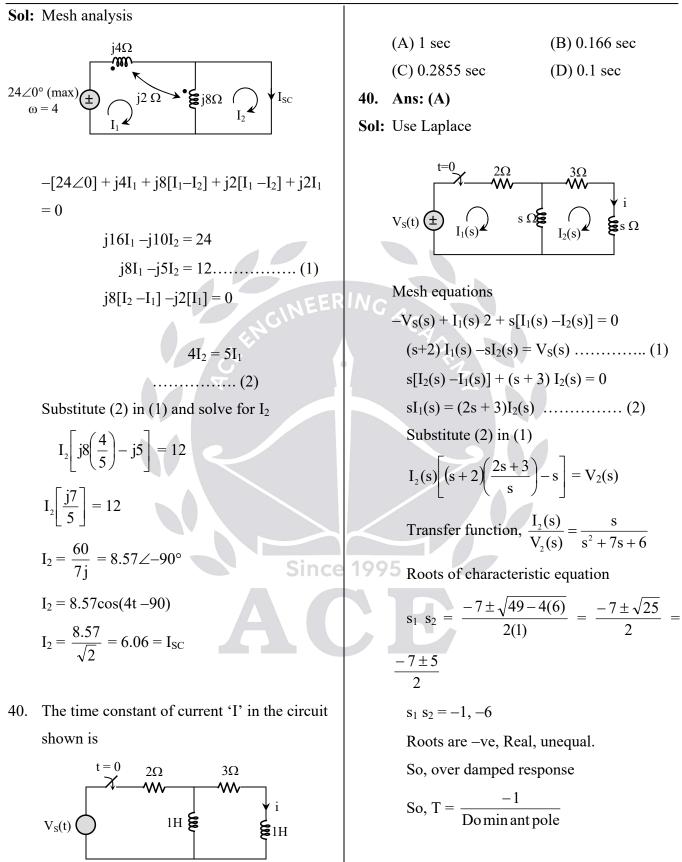
Peak value of the fundamental current component, $I_{S1} = \frac{V_m}{R} = \frac{230 \times \sqrt{2}}{10}$ = 32.52 A

38. Obtain Thevinin's equivalent at terminals a
 -b





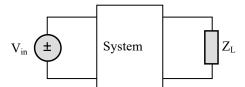






$$\mathbf{T} = -\frac{1}{(-1)} = 1 \text{ second.}$$

41.



system has transmission matrix А $\begin{bmatrix} 2 & 1+j \\ 1 & 1+\frac{j}{2} \end{bmatrix}$

If input voltage is 50 V (RMS) the maximum power transferred to the load is W.

(Range: 310 to 315) 41. Ans: 312.5

Sol:
$$V_{Th} = \frac{V_{in}}{A} = \frac{50}{2} = 25 \text{ V (RMS)}$$

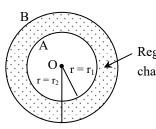
$$Z_{Th} = \frac{B}{A} = \left\lceil \frac{1+j}{2} \right\rceil \Omega$$

For $P_{max} Z_L = Z_{Th}^*$

$$Z_{L} = \left[\frac{1-j}{2}\right] \Omega$$
$$P_{max} = \frac{V_{Th}^{2}}{4R_{Th}} = \frac{(25)^{2}}{4\left(\frac{1}{2}\right)}$$

_ (25)(25)

Choosing infinity as the reference point, the 42. electric potential (in Joules/coulomb) at the origin considering only the electric field in the region outside $(r = r_2)$ is



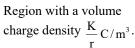


Fig. 1: Charge distribution in free space.

A & B: Spherical surfaces with radii as shown.

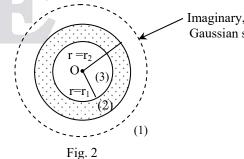
(C)∞

(B) $\frac{K}{2\epsilon_0} \frac{\left(r_2^2 - r_1^2\right)}{r_2}$ (D) $\frac{K}{6\epsilon_0} \frac{r_2^3 - r_1^3}{r_2^2}$

Ans: (B)

Since

Sol: i). Regions (1), (2) and (3) are shown in fig. 2. In each region, we can find the 1995 electric field. But in this problem, we need the field in region (1) only.



Imaginary, closed Gaussian surface

Since charge density varies only with r, the problem has spherical symmetry and hence



Gauss's law methods can be used advantageously.

Region (1): Consider a spherical Gaussian surface (imaginary, closed) with center at O (origin) and radius $r > r_2$, as shown in fig. 2. Total charge enclosed by this surface =

$$\int_{r=r_1,\theta=0,\phi=0}^{r_2,\pi,2\pi} \frac{K}{r} r^2 \sin\theta \, dr \, d\theta \, d\phi$$
$$= 4\pi K \int_{r=r_1}^{r_2} r dr = 2\pi K \left(r_2^2 - r_1^2\right) C$$

To any point on this Gaussian surface, this charge appears as a point charge at the origin. Hence electric field at a point (r, θ ,

$$\phi) \text{ in region-1} = \frac{2\pi K(r_2^2 - r_1^2)}{4\pi \epsilon_0 r^2} a_r \text{ N/C}$$

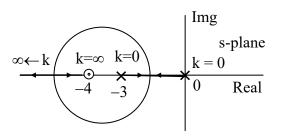
Potential at the origin, with infinity as reference is

$$V_{0} = -\int_{r=\infty,\theta=0,\phi=0}^{r_{2},\pi,2\pi} \frac{2\pi K(r_{2}^{2}-r_{1}^{2})}{4\pi\epsilon_{0}r^{2}}a_{r} \cdot (dr a_{r}+r d\theta)$$

 $a_{\theta} + r\sin\theta \, d\phi \, a_{\phi}) \dots \dots (1)$ (Upper limit for r is r_2 because we are considering field in region-1 only).

$$= -\int_{r=\infty}^{r_2} \frac{2\pi K (r_2^2 - r_1^2)}{4\pi\epsilon_0 r^2} dr$$
$$= \frac{2\pi K}{4\pi\epsilon_0} (r_2^2 - r_1^2) \frac{1}{r} \bigg]_{\infty}^{r_2}$$
$$= \frac{K (r_2^2 - r_1^2)}{2\epsilon_0 r_2}$$

43. The root loci diagram of a system is given below



What is the value of 'k' to obtain a maximum peak overshoot to a unit step input

(A)
$$k = 1$$

(B) $k = 3$
(C) $k = 5$
(D) $k = 9$
Ans: (B)
Sol:
At this point peak
Overshoot is maximum

$$\phi = maximum$$

1995 Centre of circle = (-4, 0)

Break points,
$$\frac{dk}{ds} = 0$$

 $\frac{d}{ds} \left(\frac{s(s+3)}{(s+4)} \right) = 0$
 $s^2 + 8s + 12 = 0$
 $s = -2, -6$
Radius $= \frac{6-2}{2} = 2$
 $\omega_n = \sqrt{4^2 - 2^2} = \sqrt{12}$
CE = s(s+3) + k(s+4) = 0



$$s^{2} + 3s + ks + 4k = 0$$

$$s^{2} + (k+3)s + 4k = 0$$

$$\omega_{n}^{2} = 4k = 12$$

$$k = 3$$
44. Consider the control system shown in figure below.
R(s) + k = (k+1)(s+2)(s+3)
The minimum steady state error to a unit step input is
(A) 0.35 (B) 0.54
(C) 0.09 (D) 0.1
44. Ans: (C)
Sol: CE = 1 + k
(s+1)(s+2)(s+3) = 0
s^{3} + 6s^{2} + 11s + 6k = 0
(11) (6) = 6+k
k = 60
maximum value of 'k' for stability
- 59.9999 = 60
Steady state error e_n = $\frac{1}{1+k_{n}}$

$$k_{p} = \lim_{s \to 1} \frac{k}{(s+1)(s+2)(s+3)} = \frac{k}{6}$$

$$c_{nn} = \frac{1}{1+\frac{k}{6}}$$
To obtain minimum c_{nn}, k = 60
To obtain minimum c_{nn}, k = 60
Comparison of the system is to show of the system is to shift up by +20 dB
20 log k - 20 log $\omega_{low-0.1} = 12 + 20 - 32 dB$

ACE Engineering Academy

Hearty Congratulations to our GATE-2019 Top Rankers





 $20 \log k = 12 dB$ k = 4

46.

Sol:

46. Assume diodes are ideal in the circuit shown. Find the UTP and LTP values of the circuit shown in figure.

inverting terminal is called LIP voltage. v
inverting terminal is called LIP voltage. v
inverting terminal is called LIP voltage. v

$$= -15V. D_1 - ON - (SC)$$

 $D_2 - OFF - (OC)$
 $D_2 - OFF - (OC)$
 $V_1 \bigoplus_{k} (C) = -15V$
 $V_2 \bigoplus_{k} (C) = -15V$
 $V_1 \bigoplus_{k} (C) = -15V$
 $V_1 \bigoplus_{k} (C) = -15V$
 $V_2 \bigoplus_{k} (C) = -15V$
 $V_1 \bigoplus_{k} (C) = -15V$
 $V_2 \bigoplus_{k} (C) = -15V$
 $V_1 \bigoplus_{k} (C) = -15V$
 $V_2 \bigoplus_{k} (C) = -1$

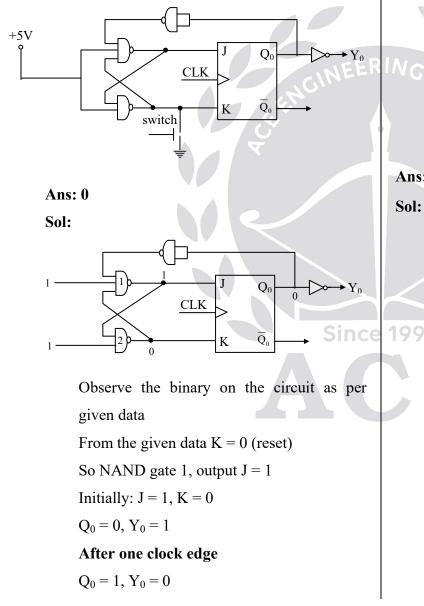
$$= 2 + (15 - 2) \left(\frac{6k}{8.4k} \right)$$
$$= 2 + 13 \left(\frac{6}{8.4} \right) = 11.28 \text{ V} \approx 11.3 \text{ V}$$

When the op-amp operated in negative saturation region, the voltage at non-inverting terminal is called LTP voltage. V_0



GATE-2020 Electrical Engineering (EE)

48. In the circuit shown, the input clock frequency is 9.7 MHz, the propagation delay of the logic gates and flip-flop's are 0 sec. Initially Q_0 is cleared to **'**0**'** and simultaneously the input 'K' is also cleared to '0'(with the help of push button toggle switch). The frequency of the wave form at ' Y_0 ' is (Hz)



But still(from circuit)
$$\begin{cases} J = 1 \\ K = 0 \end{cases}$$

Irrespective of number of clock pulses

 $Q_0 = 1, Y_0 = 0$ (always)

$$J = 1, K = 0$$

- $Y_0 = 0$ Hz (DC line with logic '0')
- 49. Let a signal x(t) be defined as X(t) = $e^{\frac{t}{2}}u(t)$. Then the energy in the frequency band $-\pi/8 \le \omega \le \pi/8$ rad/sec is

(A)
$$\frac{1}{\pi}$$
 (B) $\frac{1}{2\pi}$
(C) $\frac{4}{\pi}$ (D) $\frac{2}{\pi}$

Ans: (D)

Sol:
$$x(t) = e^{-t/2}u(t)$$

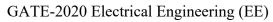
According Parseval's Theorem $E_t = E_{\omega}$

$$E_{\omega} = \frac{1}{2\pi} \int_{-\infty}^{\infty} |X(\omega)|^2 d\omega$$

$$E_{\omega} = \frac{1}{2\pi} \int_{-\frac{\pi}{8}}^{\frac{\pi}{8}} |X(\omega)|^2 d\omega$$
$$E_{\omega} = \frac{1}{2\pi} \sum |X(\omega)|^2 = -\frac{1}{2\pi}$$

$$E_{\omega} = \frac{1}{\frac{1}{2} + j\omega} \Longrightarrow |X(\omega)|^2 = \frac{1}{\frac{1}{4} + \omega^2}$$

$$\therefore E_{\omega} = \frac{1}{2\pi} \int_{-\frac{\pi}{8}}^{\frac{\pi}{8}} \frac{1}{\frac{1}{4} + \omega^2} d\omega$$



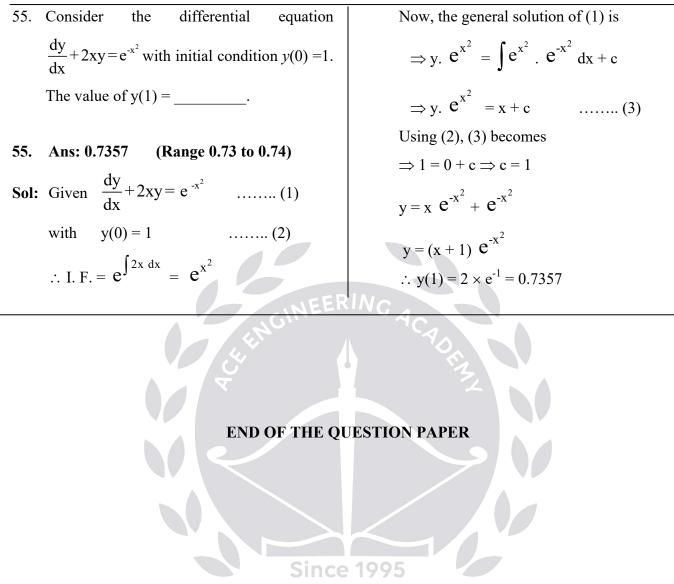




GATE-2020 Electrical Engineering (EE)

52. The value of the double
integral
$$\int_{0}^{y} \left(\int_{y/2}^{y/2} \left(\frac{2x - y}{2} \right) dx \right) dy$$
, using the
substitution $u = \left(\frac{2x - y}{2} \right) dx dy$, using the
substitution $u = \left(\frac{2x - y}{2} \right) and v = \frac{y}{2}$ or
otherwise is ______.
52. Ans: 4 (No range)
53. The surface integral $\int_{1}^{y} \left(\frac{x - y}{2} \right) dx dy = \frac{4}{y}$ and $dy = 2 dv$.
If $x = \frac{y}{2}$ then $u = 0$
If $y = 0$ then $v = 0$
If $y = 8$ then $v = 4$
53. The surface integral $\int_{1}^{y} \left(\frac{F.\pi}{R} \right) dS$ over the
surface S of the sphere $x^{2} + y^{2} + z^{2} = 9$,
where $F = (x+y)\tilde{i} + (x+z)\tilde{j} + (y+z)\tilde{k}$ and
 π is the unit outward surface normal, yields
Ans: 226.08 (Range 225 to 227)
S0: $\tilde{F} = (x + y)\tilde{i} + (x + z)\tilde{j} + (y + z)\tilde{k}$ and
 $\tilde{r} = is the unit outward surface normal, yields
 $\tilde{F} = \left(x + y \right)\tilde{i} + (x + z)\tilde{j} + (y + z)\tilde{k}$ div $\tilde{F} = 1 + 1 = 2$$





Hearty Congratulations to our ESE-2019 Top Rankers



KARTIKEYA SINGH EE







AMARJEET CE



RAJAT SONI

E&T

AIR



SAHIL GOYAL ME



AIR

HARSHAL BHOSALE (ME)



ABHISHEK ANAND EE





ROHIT KUMAR E&T

ABUZAR GAFFARI CE





HEMANT KUMAR SINGH ME

AIR

AIR



YOGESH KUMAR CE



RAHUL JAIN E&T



AIR



RITESH LALWANI EE



PUSHPAK

ME

KULDEEP KUMAR E&T



DWEEP SABAPARA ME

and many more ...



Total Selections in Top 10: 33 EE:9 E&T:8 ME:9 CE:7

KUMAR MAYANK EE

AIR





AIR



DEEPITA ROY (EE)





SHUBHAM KARNANI E&T)